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Not Used Very Often In Adaptive Control: $X(k) = A \ X(k-1) + B \ U(k-1) \ Y(k) = CTx(k)$ The ARMAX Model Can Also Be Written In State-space Form. One Of The Advantages Of The State-space Representation Is That It Simplifies The Prediction. However, System Identification Is More Complex For A State-space Model Than For A Transfer Function Model. Jun 2th, 2024

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